# CS4102 Algorithms Spring 2020

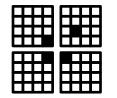
Today's Keywords

- Reductions
- Bipartite Matching
- Vertex Cover
- Independent Set

**CLRS Readings** 

• Chapter 34

# Divide and Conquer\*

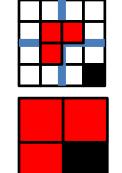


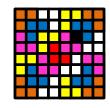
 Break the problem into multiple subproblems, each smaller instances of the original

#### • Conquer:

**Divide:** 

- If the suproblems are "large":
  - Solve each subproblem recursively
- If the subproblems are "small":
  - Solve them directly (base case)
- Combine:
  - Merge together solutions to subproblems





# Dynamic Programming

- Requires Optimal Substructure
  - Solution to larger problem contains the solutions to smaller ones
- Idea:
  - 1. Identify recursive structure of the problem
  - 2. Select a good order for solving subproblems
    - Usually smallest problem first

# Greedy Algorithms

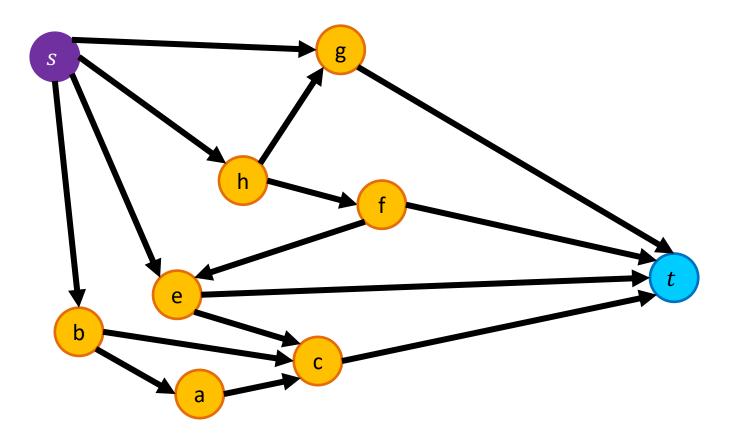
- Require Optimal Substructure
  - Solution to larger problem contains the solution to a smaller one
  - Only one subproblem to consider!
- Idea:
  - 1. Identify a greedy choice property
    - How to make a choice guaranteed to be included in some optimal solution
  - 2. Repeatedly apply the choice property until no subproblems remain

So far

- Divide and Conquer, Dynamic Programming, Greedy
  - Take an instance of *Problem A*, relate it to smaller instances of *Problem A*
- Next:
  - Take an instance of *Problem A*,
    relate it to an instance of *Problem B*

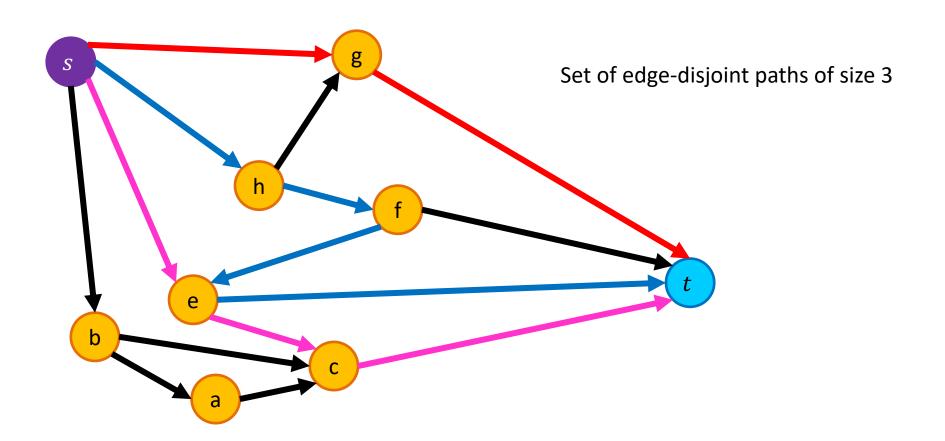
# Edge-Disjoint Paths

Given a graph G = (V, E), a start node s and a destination node t, give the maximum number of paths from s to t which share no edges



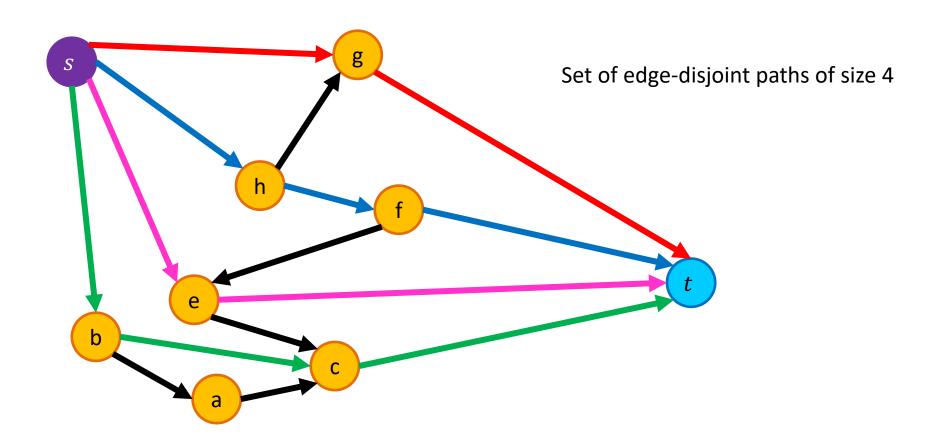
# Edge-Disjoint Paths

Given a graph G = (V, E), a start node s and a destination node t, give the maximum number of paths from s to t which share no edges



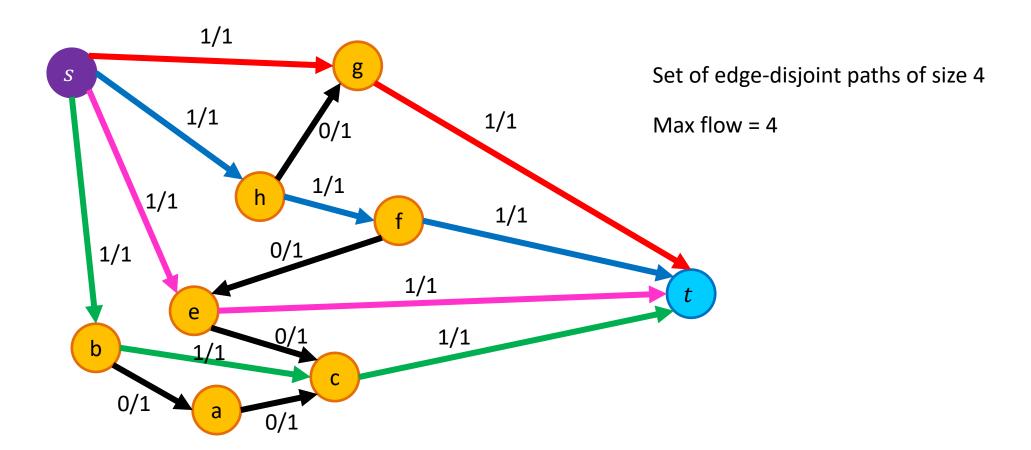
# Edge-Disjoint Paths

Given a graph G = (V, E), a start node s and a destination node t, give the maximum number of paths from s to t which share no edges



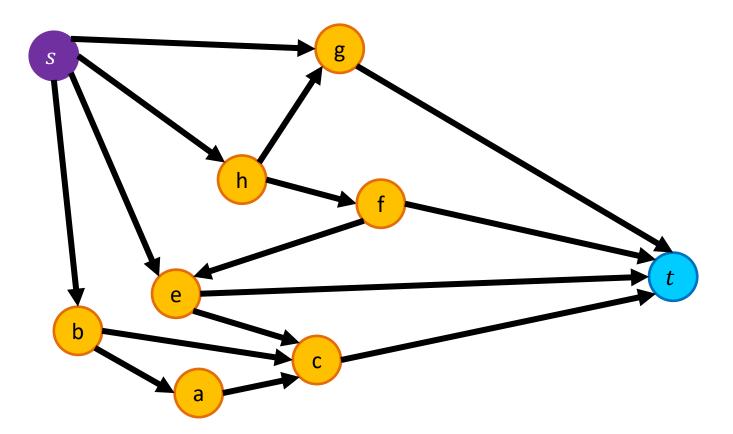
# Edge-Disjoint Paths Algorithm

Make *s* and *t* the source and sink, give each edge capacity 1, find the max flow.



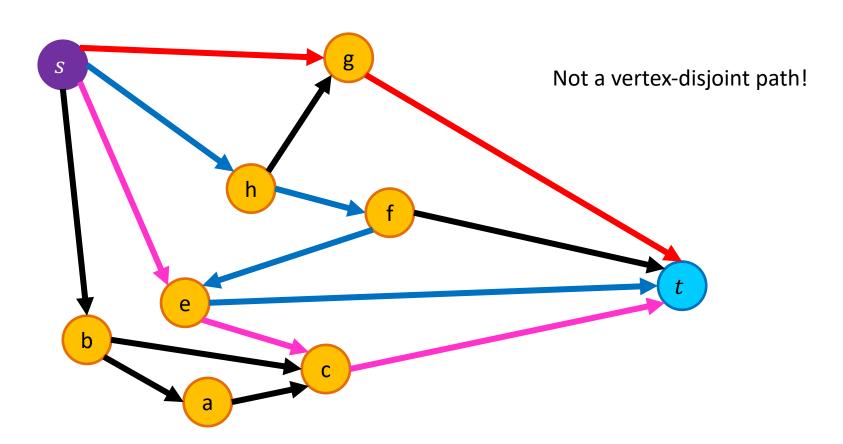
#### Vertex-Disjoint Paths

Given a graph G = (V, E), a start node s and a destination node t, give the maximum number of paths from s to t which share no vertices



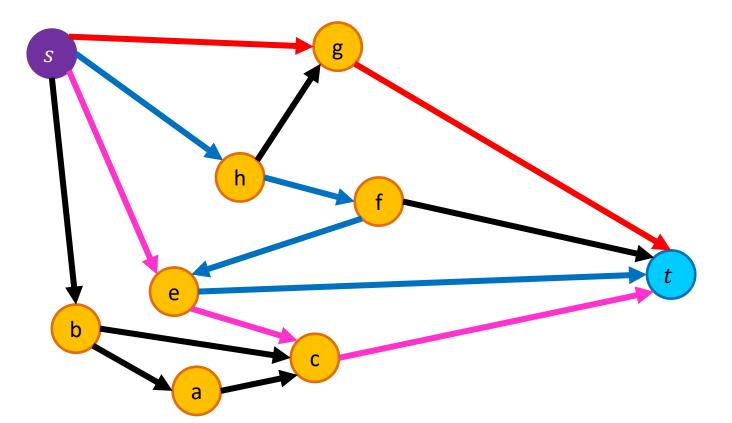
#### Vertex-Disjoint Paths

Given a graph G = (V, E), a start node s and a destination node t, give the maximum number of paths from s to t which share no vertices



## Vertex-Disjoint Paths Algorithm

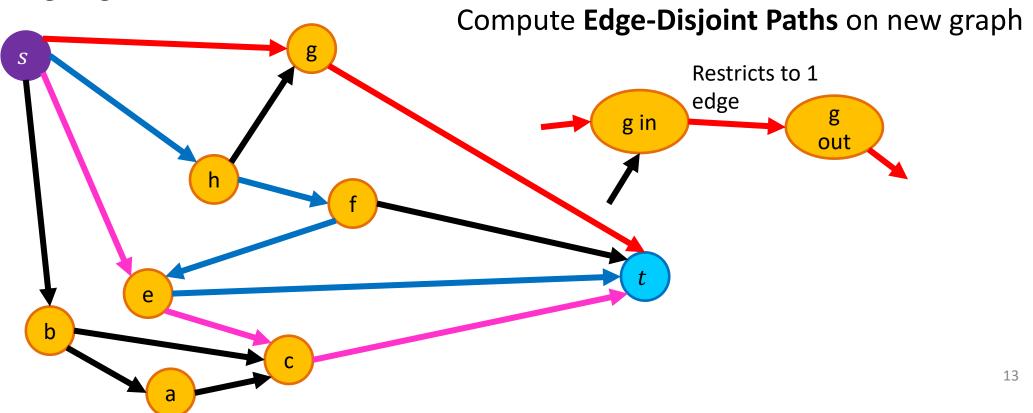
Idea: Convert an instance of the vertex-disjoint paths problem into an instance of edge-disjoint paths



# Vertex-Disjoint Paths Algorithm

Idea: Convert an instance of the vertex-disjoint paths problem into an instance of edge-disjoint paths

Make two copies of each node, one connected to incoming edges, the other to outgoing edges



Dog Lovers

Dogs



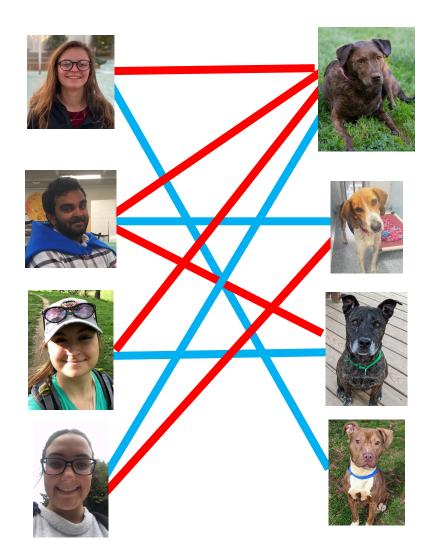
Dog Lovers

Dogs



Dog Lovers

Dogs



Given a graph G = (L, R, E)

a set of left nodes, right nodes, and edges between left and right Find the largest set of edges  $M \subseteq E$  such that each node  $u \in L$ or  $v \in R$  is incident to at most one edge.

# Maximum Bipartite Matching Using Max Flow

Make G = (L, R, E) a flow network G' = (V', E') by:

• Adding in a source and sink to the set of nodes:

 $- V' = L \cup R \cup \{s, t\}$ 

• Adding an edge from source to L and from R to sink:

$$- E' = E \cup \{u \in L \mid (s, u)\} \cup \{v \in r \mid (v, t)\}$$

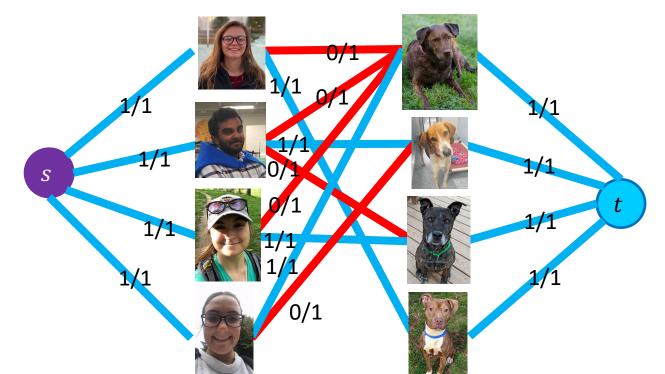
S

• Make each edge capacity 1:

$$- \forall e \in E', c(e) = 1$$

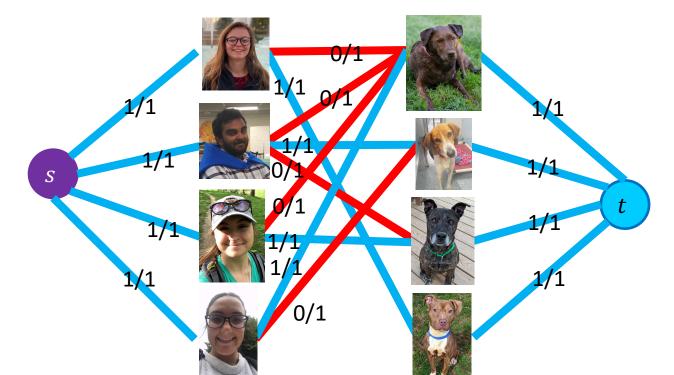
# Maximum Bipartite Matching Using Max Flow

- 1. Make G into G'
- 2. Compute Max Flow on G'
- 3. Return *M* as all "middle" edges with flow 1



# Maximum Bipartite Matching Using Max Flow

- 1. Make G into  $G' = \Theta(L+R)$
- 2. Compute Max Flow on  $G' \quad \Theta(E \cdot V) \quad |f| \leq L$
- 3. Return *M* as all "middle" edges with flow 1  $\Theta(L+R)$



 $\Theta(E \cdot V)$ 

#### Reductions

- Algorithm technique of supreme ultimate power
- Convert instance of problem A to an instance of Problem B
- Convert solution of problem B back to a solution of problem A



Shows how two different problems relate to each other



Problem we don't know how to solve



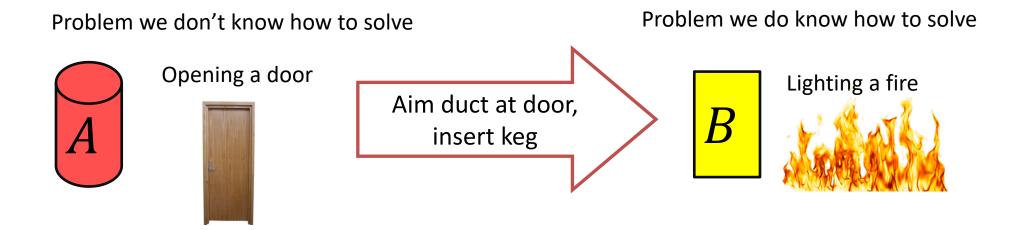
MacGyver's Reduction

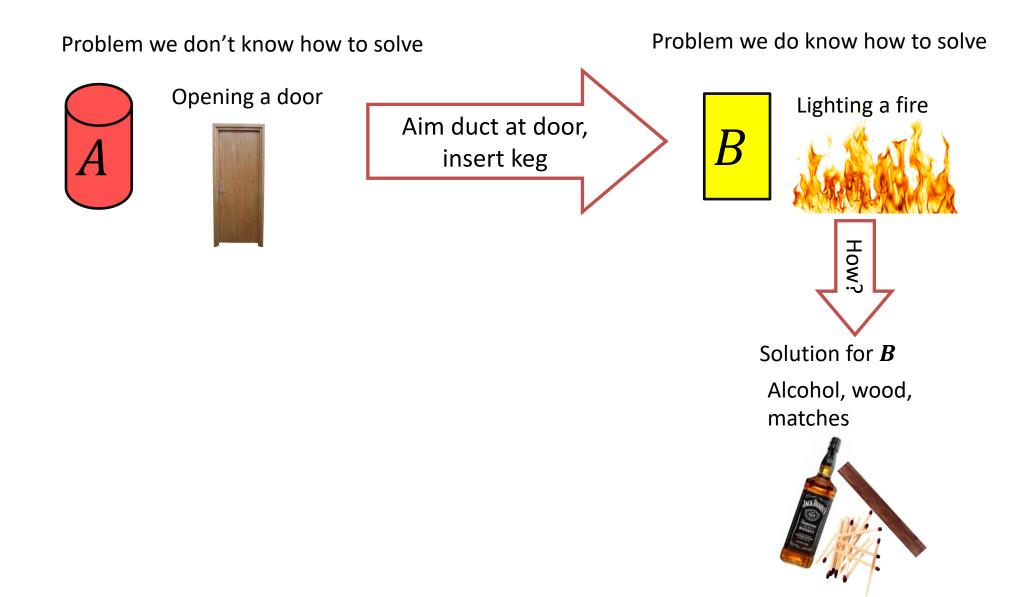
Problem we don't know how to solve

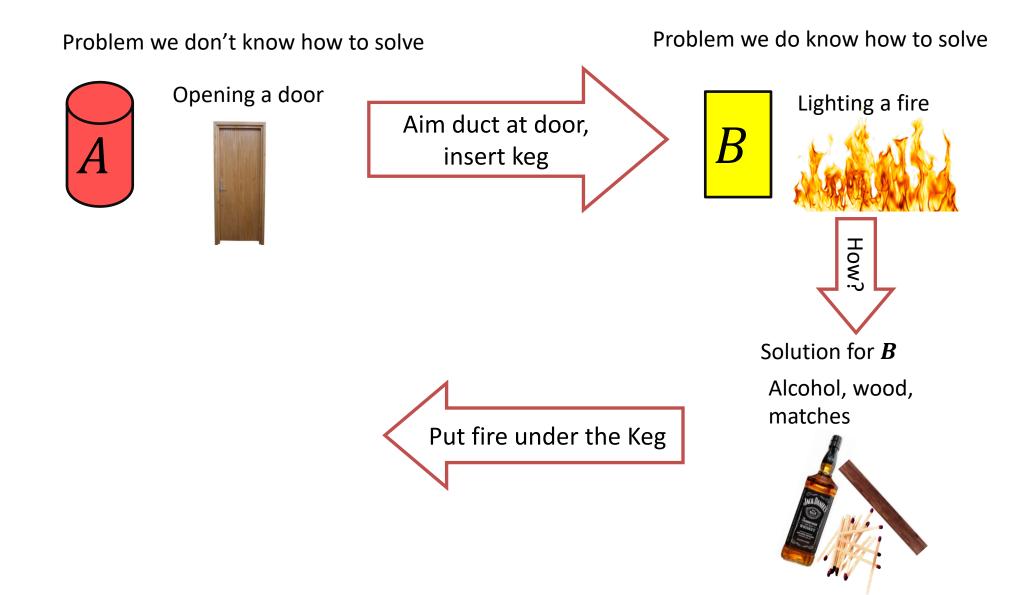


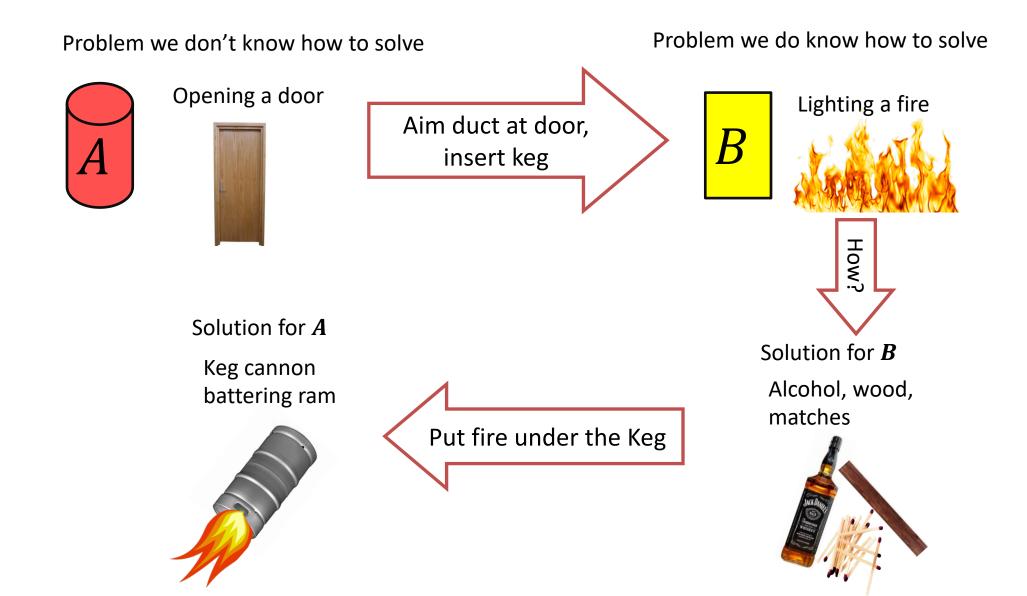
Problem we do know how to solve

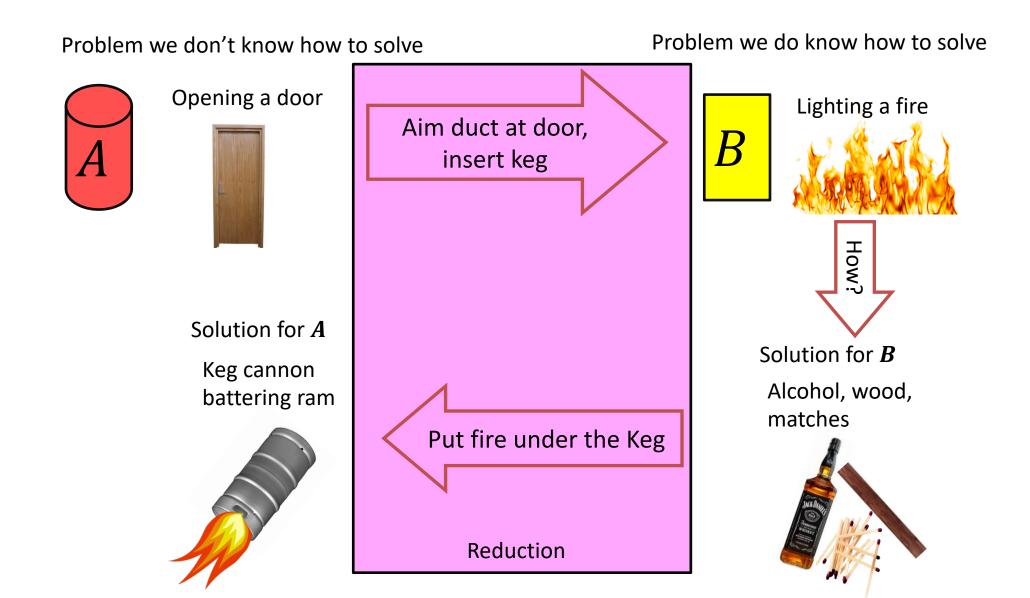




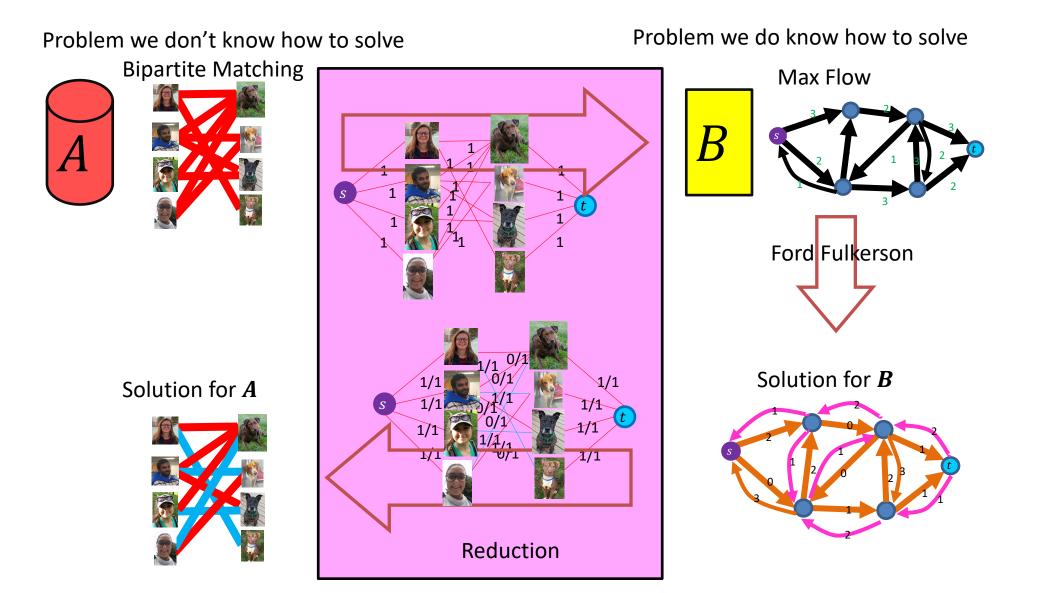




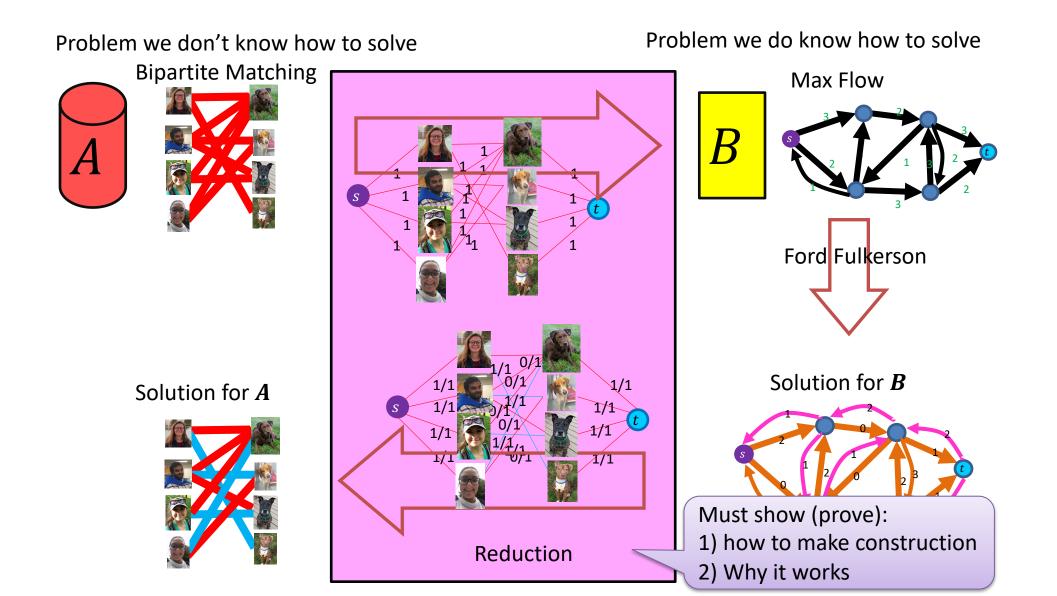




# **Bipartite Matching Reduction**



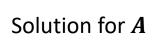
# **Bipartite Matching Reduction**



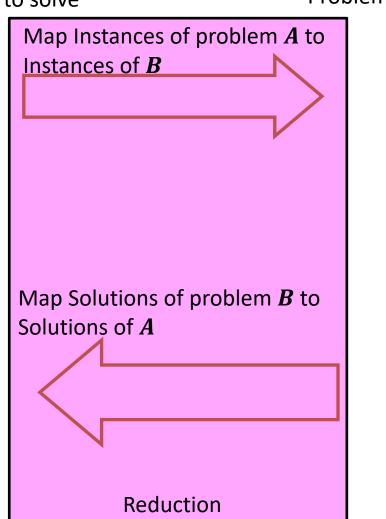
#### In General: Reduction

Problem we don't know how to solve

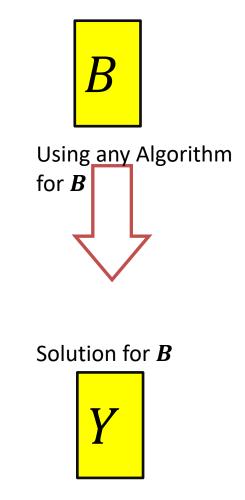








Problem we do know how to solve



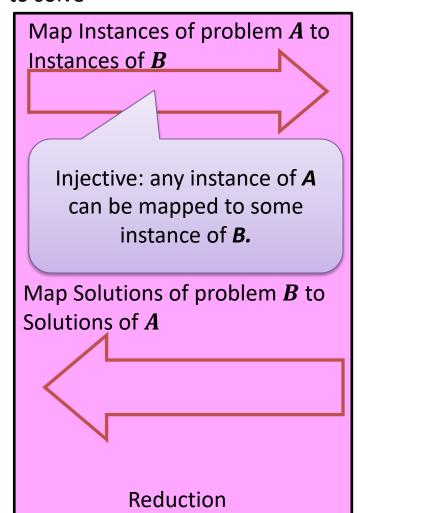
# In General: Reduction

Problem we don't know how to solve

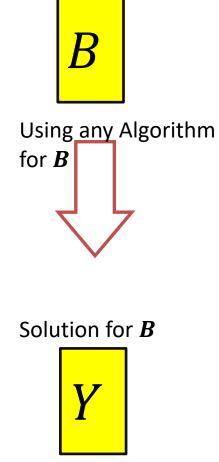


Solution for **A** 

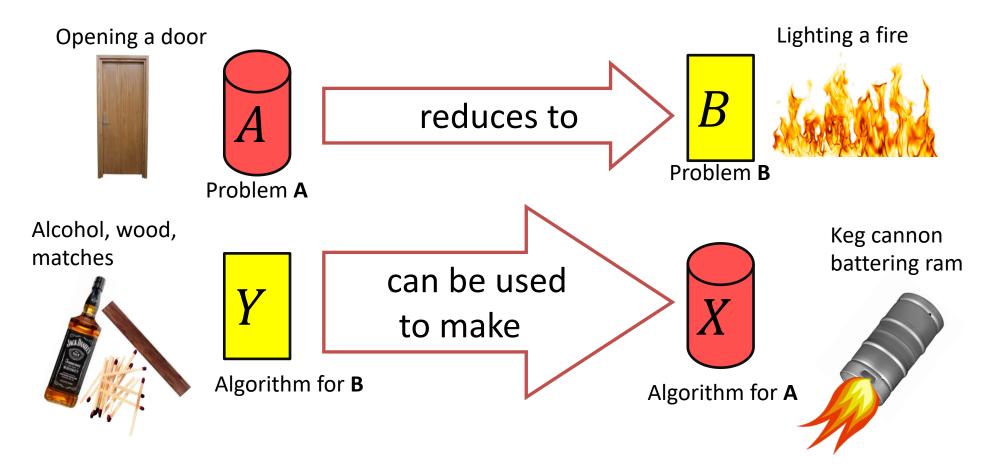




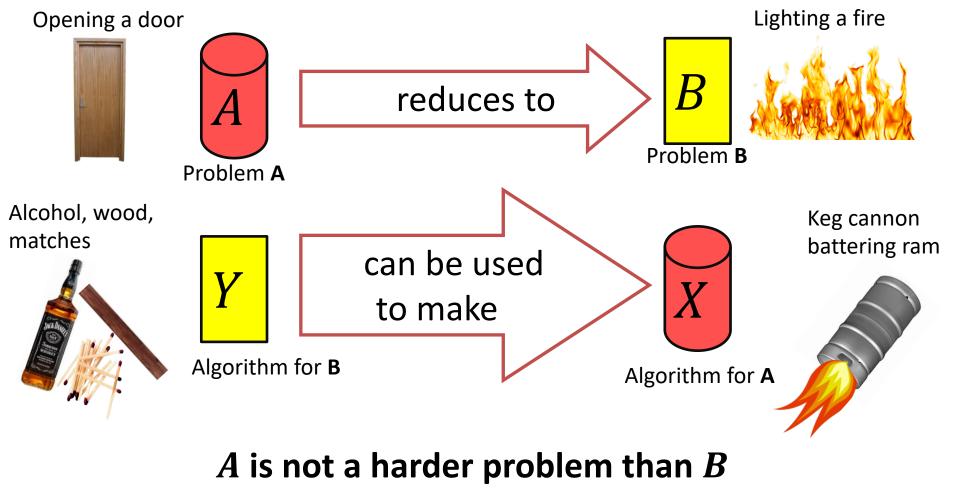
Problem we do know how to solve



#### Worst-case lower-bound Proofs

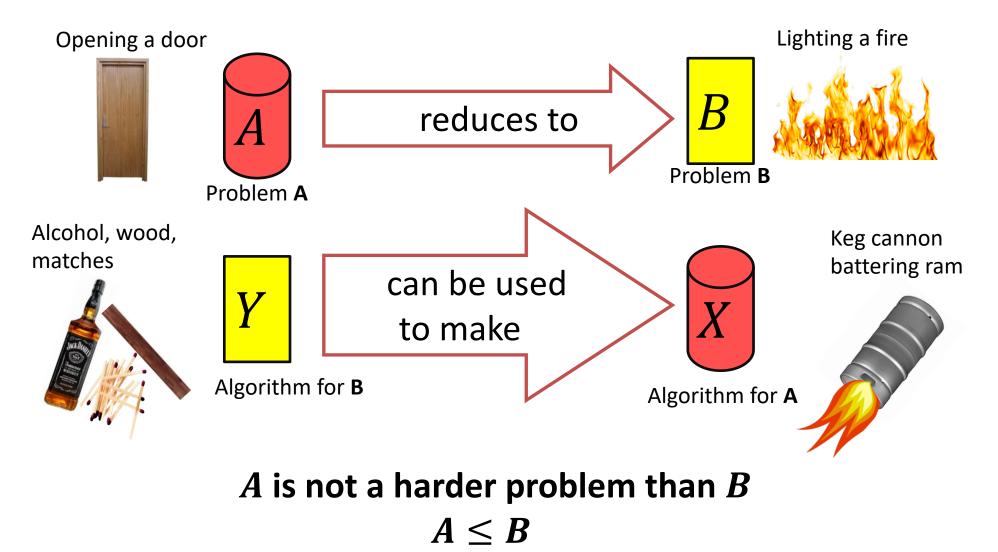


#### Worst-case lower-bound Proofs



 $A \leq B$ 

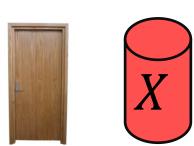
#### Worst-case lower-bound Proofs



The name "reduces" is confusing: it is in the opposite direction of the making

To Show: *Y* is slow

To Show: Y is slow



We know X is slow (by a proof)
 (e.g., X = some way to open the door)

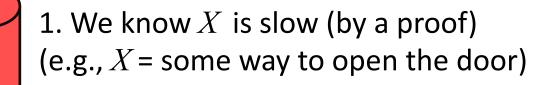
To Show: Y is slow



1. We know X is slow (by a proof)(e.g., X = some way to open the door)

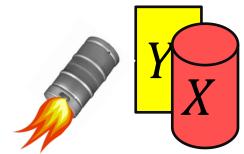
2. Assume Y is quick [toward contradiction](Y = some way to light a fire)

To Show: Y is slow



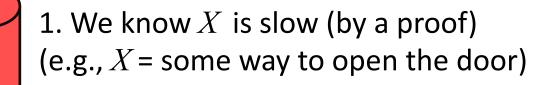


2. Assume *Y* is quick [toward contradiction] (*Y* = some way to light a fire)



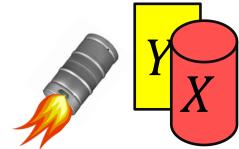
3. Show how to use *Y* to perform *X* quickly

To Show: Y is slow





2. Assume Y is quick [toward contradiction](Y = some way to light a fire)



3. Show how to use *Y* to perform *X* quickly

4. X is slow, but Y could be used to perform X quickly conclusion: Y must not actually be quick